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Publications

Distributed agency in HRI—an exploratory study of a narrative robot design

Graf, P., Zarp-Falden, C. S., Naik, L., Lefevre, K. B., Marchetti, E., Hornecker, E., Sørensen, M. B., Hemmingsen, L. V., Christensen, E. V. J., Bodenhagen, L., Krüger, N. & Bischof, A., 28. Feb 2024, In: *Frontiers in Robotics and AI*. 11, 13 p.

Planning Base Poses and Object Grasp Choices for Table-Clearing Tasks Using Dynamic Programming

Sørensen, S. L., Naik, L., Nguyen, P. K. D. T., Kramberger, A., Bodenhagen, L., Kjærgaard, M. B. & Krüger, N., Jan 2024, *Proceedings of the 16th International Conference on Agents and Artificial Intelligence*. SCITEPRESS Digital Library, Vol. 3 . p. 1316-1323

Adapted Conflict Detection for Conflict Based Search

Kollakidou, A. & Bodenhagen, L., 2024, *International Conference on Agents and Artificial Intelligence 2024*. SCITEPRESS Digital Library, p. 367-373

Bibo the Moving Cup for People Affected by Dementia: Design, Ethical Considerations, and First Observations in Use

Kollakidou, A., Lefevre, K., Zarp-Falden, C. S., Malbois, E., Bodenhagen, L., Krüger, N. & Hornecker, E., Sept 2023, In: *SN Computer Science*. 4, 5, 432.

Proactive Control for Online Individual User Adaptation in a Welfare Robot Guidance Scenario: Toward Supporting Elderly People

Zurro, A. P., Ignasov, J., Ramírez, E. R., Haarslev, F., Juel, W. K., Bodenhagen, L., Krüger, N., Shaikh, D., Rano, I. & Poramate, M., Jun 2023, In: *IEEE Transactions on Systems, Man, and Cybernetics: Systems*. 53, 6, p. 3364-3376

The Impact of Speech and Movement on the Interaction with a Mobile Hand Disinfection Robot

Bjorn, A., Juul, S. H., Arnesen, N. R., Andersen, M. S., Philipsen, R., Jelinek, M., Bodenhagen, L. & Palinko, O., 13. Mar 2023, *HRI 2023: Companion of the ACM/IEEE International Conference on Human-Robot Interaction*. Association for Computing Machinery, p. 373-377

Improving Throughput of Mobile Robots in Narrow Aisles

Thomsen, S., Davidsen, M., Naik, L., Kollakidou, A., Bodenhagen, L. & Krüger, N., 2023, *Proceedings of the 18th International Joint Conference on Computer Vision, Imaging and Computer Graphics Theory and Applications - HUCAPP*. Paljic, A., Ziat, M. & Bouatouch, K. (eds.). SCITEPRESS Digital Library, Vol. 2. p. 221-228 (IVAPP, Vol. 2).

Toward Human-Centered Collaborative Robotics for Manufacturing

Pietras, E. T. J. S., Ulfert-Blank, A-S., Kramberger, A., Krüger, N. & Bodenhagen, L., 2023.

Understanding human-robot teamwork in the wild: The difference between success and failure for mobile robots in hospitals

Tornbjerg, K. & Bodenhagen, L., 2023, *2023 32nd IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)*. IEEE, p. 277-284 (IEEE RO-MAN proceedings).

Analysis and Utilisation of Conflicts in Multi-Agent Path Finding

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Testing the dancing cup "Bibo" to reduce dehydration of dementia patients

Kollakidou, A., Zarp-Falden, C. S., Lefevre, K., Bodenhagen, L., Krüger, N. & Hornecker, E., May 2022.

A Mobile Social Hand Disinfection Robot for Use in Hospitals

Palinko, O., Junge, R. P., Holm, D. G. & Bodenhagen, L., 2022, *Social Robotics - 14th International Conference, ICSR 2022, Proceedings*. Cavallo, F., Cabibihan, J.-J., Fiorini, L., Sorrentino, A., He, H., Liu, X., Matsumoto, Y. & Ge, S. S. (eds.). Springer Nature, p. 348-358 (Lecture Notes in Computer Science, Vol. 13818).

Health-CAT: Development of a Mobile Robot for Assisting Caregivers

Juel, W. K., Haarslev, F. & Bodenhagen, L., 2022, *Proceedings of the 17th International Joint Conference on Computer Vision, Imaging and Computer Graphics Theory and Applications - HUCAPP*. SCITEPRESS Digital Library, Vol. 2. p. 171-178 (IVAPP, Vol. 2).

HRI-Gestures: Gesture Recognition for Human-Robot Interaction

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Intention Understanding for Human-Aware Mobile Robots: Comparing Cues and the Effect of Demographics

Palinko, O., Ramirez, E. R., Krüger, N. & Bodenhagen, L., 2022, *Computer Vision, Imaging and Computer Graphics Theory and Applications : 15th International Joint Conference, VISIGRAPP 2020, Revised Selected Papers*. Bouatouch, K., de Sousa, A. A., Chessa, M., Paljic, A., Kerren, A., Hurter, C., Farinella, G. M., Radeva, P. & Braz, J. (eds.). Springer Science+Business Media, p. 83-102 (Communications in Computer and Information Science, Vol. 1474 CCIS).

Negotiating Personal Space Invasions in Crowded Environments

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What Will It Take to Help a Stuck Robot? Exploring Signaling Methods for a Mobile Robot

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Enabling robots to adhere to social norms by detecting F-formations

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Naik, L., Palinko, O., Bodenhagen, L. & Kruger, N., 8. Aug 2021, *2021 30th IEEE International Conference on Robot and Human Interactive Communication, RO-MAN 2021*. IEEE, p. 323-329

A robotic interface for motivating and educating proper hand sanitization using speech and gaze interaction

Palinko, O., Fredskild, T. U., Andersen, E. T., Heidtmann, C., Sorensen, A. R., Peter Junge, R., Nielsen, N. H. T., Bodenhagen, L. & Kruger, N., 2021, *2021 30th IEEE International Conference on Robot and Human Interactive Communication, RO-MAN 2021*. IEEE, p. 763-769 (IEEE RO-MAN proceedings).

Context-Aware Social Robot Navigation

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Fischer, K., Seibt, J., Rodogno, R., Kirkegård Rasmussen, M., Weiss, A., Bodenhagen, L., Juel, W. K. & Krüger, N., Jan 2020, In: *Interaction Studies*. 21, 1, p. 145-185

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Human-Aware Robot Behavior in Healthcare Facilities

Haarslev, F., Juel, W. K., Kollakidou, A., Krüger, N. & Bodenhagen, L., 2020.

Intention Indication for Human Aware Robot Navigation

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Synthetic Ground Truth for Presegmentation of Known Objects for Effortless Pose Estimation

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The Penguin – on the boundary between pet and machine: An ecological perspective on the design of assistive robots for elderly care

Marchetti, E., Juel, W. K., Langedijk, R. M., Bodenhagen, L. & Krüger, N., Jul 2019, *Human Aspects of IT for the Aged Population. Social Media, Games and Assistive Environments. HCII 2019*. Salvendy, G. & Zhou, J. (eds.). Springer, Vol. Part II. p. 425-443 (Lecture Notes in Computer Science, Vol. 11593).

Robot Technology For Future Welfare: Meeting Upcoming Societal Challenges - An Outlook With Offset In The Development In Scandinavia

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Concurrent intramodal learning enhances multisensory responses of symmetric crossmodal learning in robotic audio-visual tracking

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Robot use cases for real needs: A large-scale ethnographic case study

Bodenhagen, L., Fischer, K., Winther, T. S., Langedijk, R. M. & Skjøth, M. M., 2019, In: *Paladyn: Journal of Behavioral Robotics*. 10, 1, p. 193-206

Speech melody matters: How robots profit from using charismatic speech

Fischer, K., Niebuhr, O., Jensen, L. C. & Bodenhagen, L., 2019, In: *ACM Transactions on Human-Robot Interaction*. 9, 1, 21 p., 4.

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Fernandez Coleto, N., Ramírez, E. R., Haarslev, F. & Bodenhagen, L., 2019, *Social Robotics: 11th International Conference, ICSR 2019, Madrid, Spain, November 26–29, 2019, Proceedings*. Salichs, M. A., Ge, S. S., Barakova, E. I., Cabibihan, J.-J., Wagner, A. R., Castro-González, Á. & He, H. (eds.). Springer, p. 578-587 (Lecture Notes in Computer Science, Vol. 11876).

Simulation Based Behavior for a Welfare Robot

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The SMOOTH Robot: Design for a Novel Modular Welfare Robot

Juel, W. K., Haarslev, F., Fischer, K., Marchetti, E., Shaikh, D., Manoonpong, P., Hauch, C., Bodenhagen, L. & Krüger, N., 21. May 2018.

Increasing trust in human–robot medical interactions: Effects of transparency and adaptability

Fischer, K., Mareike Weigelin, H. & Bodenhagen, L., 2018, In: *Paladyn. Journal of Behavioral Robotics*. 9, 1, p. 95-109

"I would like to get close to you": Making robot personal space invasion less intrusive with a social gaze cue

Suvei, S-D., Vroon, J., Somoza Sanchez, V. V., Bodenhagen, L., Englebienne, G., Krüger, N. & Evers, V., 2018, *Universal Access in Human-Computer Interaction. Virtual, Augmented, and Intelligent Environments - 12th International Conference, UAHCI 2018, Held as Part of HCI International 2018, Proceedings*. Antona, M. & Stephanidis, C. (eds.). Springer, p. 366-385 (Lecture Notes in Computer Science, Vol. 10908).

Robots for elderly care institutions

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Juel, W. K., Krüger, N. & Bodenhagen, L., 2018, *Envisioning Robots in Society – Power, Politics, and Public Space: Proceedings of Robophilosophy 2018 / TRANSOR 2018*. Coeckelbergh, M., Loh, J., Funk, M., Seibt, J. & Nørskov, M. (eds.). IOS Press, p. 221-230 (Frontiers in Artificial Intelligence and Applications, Vol. 311).

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Suvei, S-D., Haarslev, F., Bodenhagen, L. & Krüger, N., 2018, *Proceedings of the 13th International Joint Conference on Computer Vision, Imaging and Computer Graphics Theory and Applications*. Treméau, A., Imai, F. & Braz, J. (eds.). SCITEPRESS Digital Library, Vol. 4. p. 166-173

Towards A Robotic Assistant for Care-givers

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Towards Crossmodal Learning for Smooth Multimodal Attention Orientation

Haarslev, F., Docherty, D., Suvei, S-D., Juel, W. K., Bodenhagen, L., Shaikh, D., Krüger, N. & Manoonpong, P., 2018, *Social Robotics: Proceedings of the 10th International Conference, ICSR 2018*. Ge, S. S., Cabibihan, J-J., A. Salichs, M., Broadbent, E., He, H., R. Wagner, A. & Castro-González, Á. (eds.). Springer, p. 318-328 (Lecture Notes in Computer Science, Vol. 11357). (Lecture Notes in Artificial Intelligence, Vol. 11357).

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Applying Peg-in-Hole Actions with a Service Robot

Suvei, S-D., Bodenhagen, L., Thulesen, T. N., Jami, M. D. & Krüger, N., 2017, *Proceedings of the 7th International Conference on Simulation and Modeling Methodologies, Technologies and Applications*. De Rango, F., Ören, T. & Obaidat, M. S. (eds.). SCITEPRESS Digital Library, p. 224-231

Multisensory guidance of goal-oriented behaviour of legged robots

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Socially Acceptable Behaviour for Robots Approaching Humans using an Adaptable Personal Space

Camillus Jeppesen, K., Bodenhausen, L. & Krüger, N., 2017, *Proceedings of the 12th International Joint Conference on Computer Vision, Imaging and Computer Graphics Theory and Applications*. Braz, J., Richard, P. & Yamaguchi, T. (eds.). SCITEPRESS Digital Library, Vol. 2. p. 116-121

Task and Context Sensitive Gripper Design Learning Using Dynamic Grasp Simulation

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The Influence of Transparency and Adaptability on Trust in Human-Robot Medical Interactions

Bodenhausen, L., Fischer, K. & Mareike Weigelin, H., 2017. 6 p.

Unimodal Learning Enhances Crossmodal Learning in Robotic Audio-Visual Tracking

Shaikh, D., Bodenhausen, L. & Manoonpong, P., 2017. 4 p.

Using Online Modelled Spatial Constraints for Pose Estimation in an Industrial Setting

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Between Legibility and Contact: The Role of Gaze in Robot Approach

Fischer, K., Jensen, L. C., Suvei, S-D. & Bodenhausen, L., 15. Nov 2016, *Proceedings of the 25th IEEE International Symposium on Robot and Human Interactive Communication*. IEEE, p. 646-651 7745186. (IEEE RO-MAN proceedings).

Stereo and Active-Sensor Data Fusion for Improved Stereo Block Matching

Suvei, S-D., Bodenhausen, L., Kiforenko, L., Christiansen, P., Nyholm Jørgensen, R., Buch, A. G. & Krüger, N., Jul 2016, *Image Analysis and Recognition: 13th International Conference, ICIAR 2016, in Memory of Mohamed Kamel, Póvoa de Varzim, Portugal, July 13-15, 2016, Proceedings*. Campilho, A. & Karray, F. (eds.). Springer, p. 451-461 (Lecture Notes in Computer Science, Vol. 9730).

Optimizing Grippers for Compensating Pose Uncertainties by Dynamic Simulation

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Object detection using categorised 3D edges

Kiforenko, L., Buch, A. G., Bodenhausen, L. & Krüger, N., Feb 2015, *Seventh International Conference on Machine Vision, ICMV 2014: Seventh International Conference on Machine Vision (ICMV 2014)*. Verikas, A., Vuksanovic, B., Radeva, P. & Zhou, J. (eds.). SPIE - International Society for Optical Engineering, (Proceedings of SPIE, the International Society for Optical Engineering, Vol. 9445).

Trinvis og delte strategier for kontrol af velfærdsrobotter

Fischer, K., Bodenhausen, L., Krüger, N., Andersen, M. Ø. & Baumann, T., Feb 2015, In: *Medicoteknik* . 1, 2. årgang , p. 11-13 3 p.

The Role of the Timing between Multimodal Robot Behaviors for Joint Action

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An Adaptable Robot Vision System Performing Manipulation Actions with Flexible Objects

Bodenhausen, L., Fugl, A. R., Jordt, A., Willatzen, M., Aulkjær Andersen, K., Mølbach Olsen, M., Koch, R., Petersen, H. G. & Krüger, N., Jul 2014, In: *IEEE Transactions on Automation Science and Engineering*. 11, 3, p. 749 - 765

To Beep or Not to Beep is Not the Whole Question

Fischer, K., Jensen, L. C. & Bodenhausen, L., 2014, *Social Robotics: 6th International Conference, ICSR 2014, Sydney, NSW, Australia, October 27-29, 2014. Proceedings*. Beetz, M., Johnston, B. & Williams, M-A. (eds.). Springer, p. 156-165

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Probabilistic Manipulations Functions: Statistical Representation of Actions and their Outcomes

Bodenhagen, L., 2013, Syddansk Universitet. Det Naturvidenskabelige Fakultet.

Statistical Identification of Composed Visual Features Indicating High Likelihood of Grasp Success

Thomsen, M. T., Bodenhagen, L. & Krüger, N., 2013, In: IEEE International Conference on Robotics and Automation.

Learning Peg-In-Hole Actions with Flexible Objects

Bodenhagen, L., Fugl, A. R., Willatzen, M., Petersen, H. G. & Krüger, N., Feb 2012, *Proceedings of the 4th International Conference on Agents and Artificial Intelligence*. Filipe, J. & Fred, A. (eds.). SCITEPRESS Digital Library, p. 624-631

An Outline for an intelligent System performing Peg-in-Hole Actions with flexible Objects

Jordt, A., Fugl, A. R., Bodenhagen, L., Willatzen, M., Koch, R., Petersen, H. G., Andersen, K. A., Olsen, M. M. & Krüger, N., Dec 2011. 12 p.

Grasp Densities for Grasp Refinement in Industrial Bin Picking

Hupfaut, B., Hahn, H., Bodenhagen, L., Kraft, D., Krüger, N. & Piater, J., 2011.

Grasp Learning by Means of Developing Sensorimotor Schemas and Generic World Knowledge

Krüger, N., Popovic, M., Bodenhagen, L., Kraft, D. & Guerin, F., 2011, *Proceedings of AISB 2011 : Computational Models of Cognitive Development*. Society for the Study of Artificial Intelligence and the Simulation of Behaviour, p. 23-31

Learning Grasp Affordance Densities

Detry, R., Kraft, D., Kroemer, O., Bodenhagen, L., Peters, J., Krüger, N. & Piater, J., 2011, In: *Paladyn. Journal of Behavioral Robotics*. 2, 1, p. 1-17

What a successful grasp tells about the success chances of grasps in its vicinity

Bodenhagen, L., Detry, R., Piater, J. & Krüger, N., 2011, *Development and Learning (ICDL), 2011 IEEE International Conference on*. IEEE, 8 p.

A Strategy for Grasping unknown Objects based on Co-Planarity and Colour Information

Popovic, M., Kraft, D., Bodenhagen, L., Baseski, E., Pugeault, N., Kragic, D., Asfour, T. & Krüger, N., 31. May 2010, In: *Robotics and Autonomous Systems*. 58, 5, p. 551-565

Learning to Grasp Unknown Objects Based on 3D Edge Information

Bodenhagen, L., Kraft, D., Popovic, M., Baseski, E., Hotz, P. E. & Krüger, N., 2010, *IEEE International Symposium on Computational Intelligence in Robotics and Automation (CIRA2009)*. IEEE, p. 421 - 428

Using Multi-Modal 3D Contours and Their Relations for Vision and Robotics

Baseski, E., Pugeault, N., Kalkan, S., Bodenhagen, L., Piater, J. & Krüger, N., 2010, In: *Journal of Visual Communication and Image Representation*. 21, 8, p. 850-864

Using 3D Contours and Their Relations for Cognitive Vision and Robotics

Baseski, E., Bodenhagen, L., Pugeault, N., Kalkan, S., Piater, J. & Krüger, N., 2009, *Ikke angivet*. International Symposium on Computer and Information Sciences

Activities

2. Transferforum - Wirtschaft und Wissenschaft in der Kiel Region

Leon Bodenhagen (Speaker)

1. Nov 2011

A Robotic Assistant for Care-Givers

Tilia Lind Hasselager (Participant), William Kristian Juel (Participant), Christoph Zickler (Participant), Sascha Witt (Participant) & Leon Bodenhagen (Participant)
Nov 2018

DGR Days 2012

Leon Bodenhagen (Speaker)
6. Sept 2012

European Robotics Forum

Leon Bodenhagen (Speaker)
7. Mar 2012

How can the Care-O-Bot test platform inspire to develop new technology?

Leon Bodenhagen (Guest lecturer)
1. Feb 2018

IROS 2020 Workshop: Robots for Health and Elderly Care

Leon Bodenhagen (Organizer), Oskar Palinko (Organizer), François Michaud (Organizer), Adriana Tapus (Organizer) & Julie Robillard (Organizer)
29. Oct 2020

Robotterne flytter ind: Hvad skal der til?

Leon Bodenhagen (Lecturer)
18. Sept 2016

Smooth Interaction Between Humans and Robots Through Pro-Active Robot Behavior

Leon Bodenhagen (Guest lecturer)
21. May 2018

The SMOOTH Robot: Assisting Care Givers

William Kristian Juel (Participant), Frederik Haarslev (Participant), Emanuela Marchetti (Participant), Norbert Krüger (Participant) & Leon Bodenhagen (Participant)
Nov 2018

Where can robots make a difference for our welfare?

Leon Bodenhagen (Speaker) & Louise Halgaard Gottfredsen (Speaker)
10. Oct 2017